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This two volume set LNAI 9834 and 9835 constitutes the refereed proceedings of the 9th International Conference on Intelligent Robotics and Applications, ICIRA 2016, held in Tokyo, Japan, in August 2016. The 114 papers presented were carefully reviewed and selected from 148 submissions. The papers are organized in topical sections such as Robot Control; Robot Mechanism, Robot Vision and Sensing; Planning, Localization, and Mapping; Interactive Intelligence; Cognitive Robotics; Bio-Inspired Robotics; Smart Material Based Systems; Mechatronics Systems for Nondestructive Testing; Social Robotics; Human Support Robotics; Assistive Robotics; Intelligent Space; Sensing and Monitoring in Environment and Agricultural Sciences; Human Data Analysis; Robot Hand.

This book provides a comprehensive study of multi-stage and multi-time scale design of feedback controllers for linear dynamic systems. It examines different types of controllers as can be designed for different parts of the system (subsystems) using corresponding feedback gains obtained by performing calculations (design) only with subsystem (reduced-order) matrices. The advantages of the multi-stage/multi-time scale design are presented and conditions for implementation of these controllers are established. Complete derivations and corresponding design techniques are presented for two-stage/two-time-scale, three-stage/three-time scale, and four-stage/four-time-scale systems. The techniques developed have potential applications to a large number of real physical systems. The design techniques are demonstrated on examples of mathematical models of fuel cells, especially the proton exchange membrane fuel cell.

Synesthetic design strives to develop products that systematically incorporate all five senses. In future, the current wealth of medical technical insights in psychology, physiology, motor functions, and neurology and the development of innovative materials with astonishing new properties will open up almost unlimited opportunities for the designer's creativity. Haverkamp brings together for the first time precisely those aspects of this fundamental knowledge that are specifically relevant for designers. The result is a book that offers designers of all schools a clear and well-organized practical handbook and a solid foundation for their own designs.